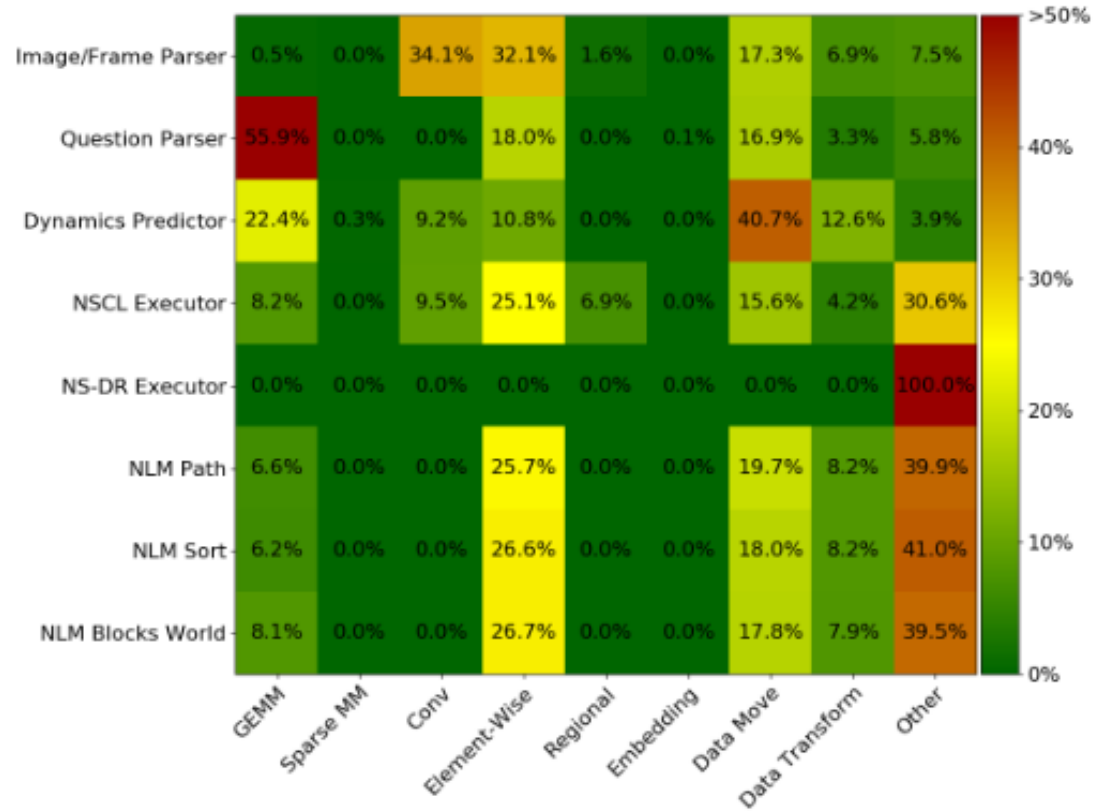


# Neuro-Symbolic AI: An Emerging Class of AI Workloads and their Characterization

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John



# Outline

## Preliminaries

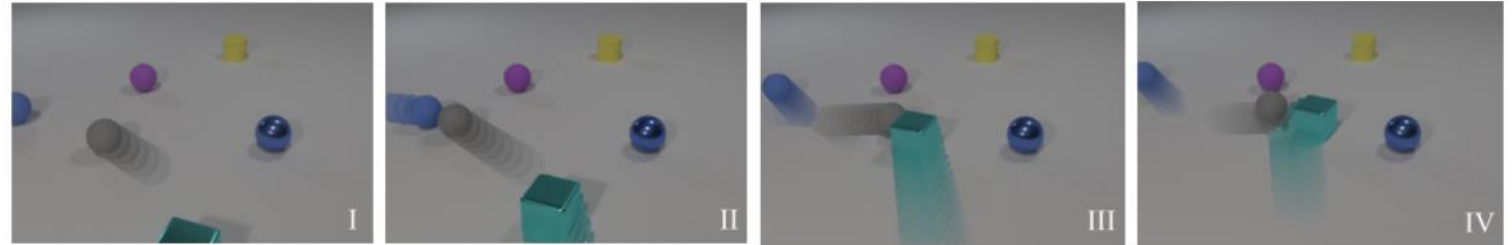
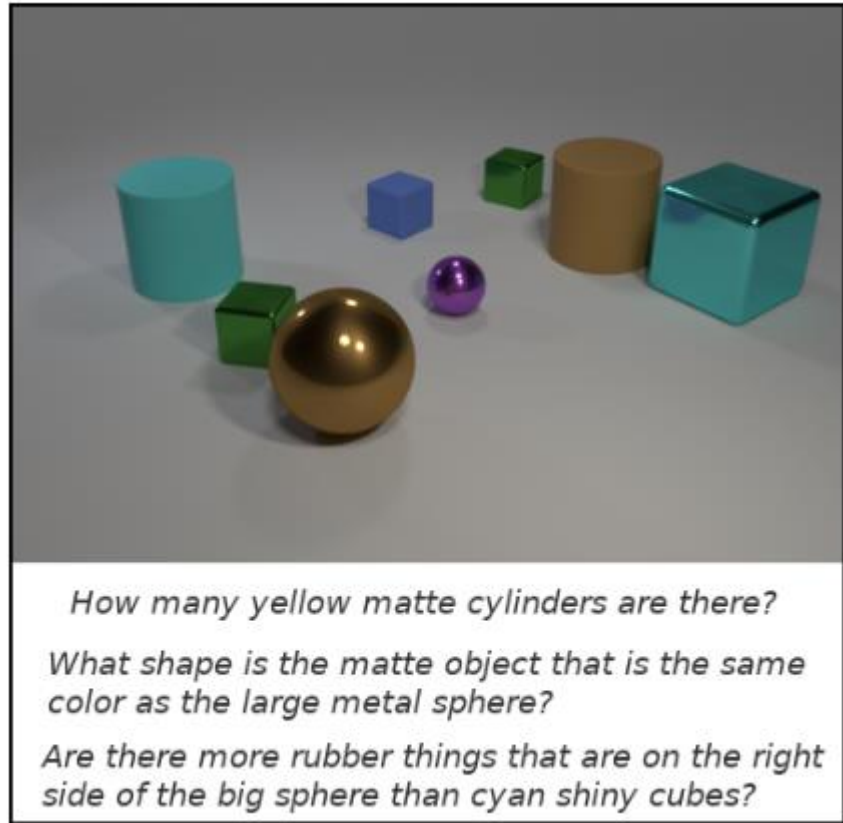
- CLEVRER; Forward Chaining
- Model and Data Parallelism

## Introduction and Motivation

## Methodology

## Results and Conclusion

# Preliminaries (models)



**Descriptive:**

**Q:** How many spheres are moving?  
**A:** 2

**Q:** What shape is the second object to collide with the gray object?  
**A:** Cube

**Q:** Are there any collisions after the cube enters the scene?  
**A:** Yes

**Explanatory:**

**Q:** Which of the following is responsible for the collision between the gray object and the cube?

a) The presence of the purple object  
 b) The collision between the blue sphere and the gray sphere  
 c) The presence of the purple object  
 d) The presence of the blue object

**A:** b), d)

**Predictive:**

**Q:** What will happen next?

a) The cube and the gray object collide  
 b) The gray sphere collides with the purple sphere  
 c) The metal sphere and the cube collide  
 d) The gray sphere collides with the blue sphere

**A:** b)

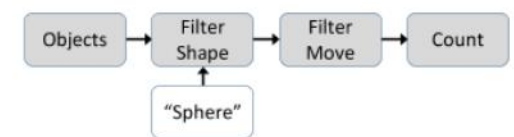
**Counterfactual:**

**Q:** What will happen if the gray sphere is removed?

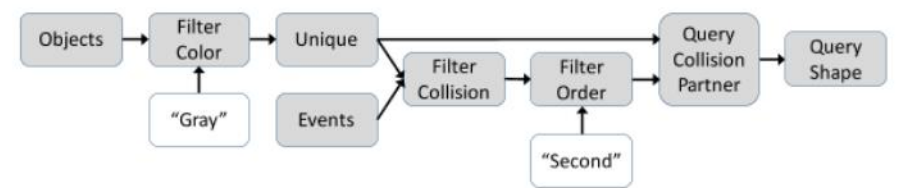
a) The blue sphere collides with the cube  
 b) The blue sphere and the metal sphere collide  
 c) The purple object collides with the cylinder  
 d) The cube and the metal sphere collide

**A:** a), d)

How many spheres are moving?



What shape is the second object to collide with the gray object?

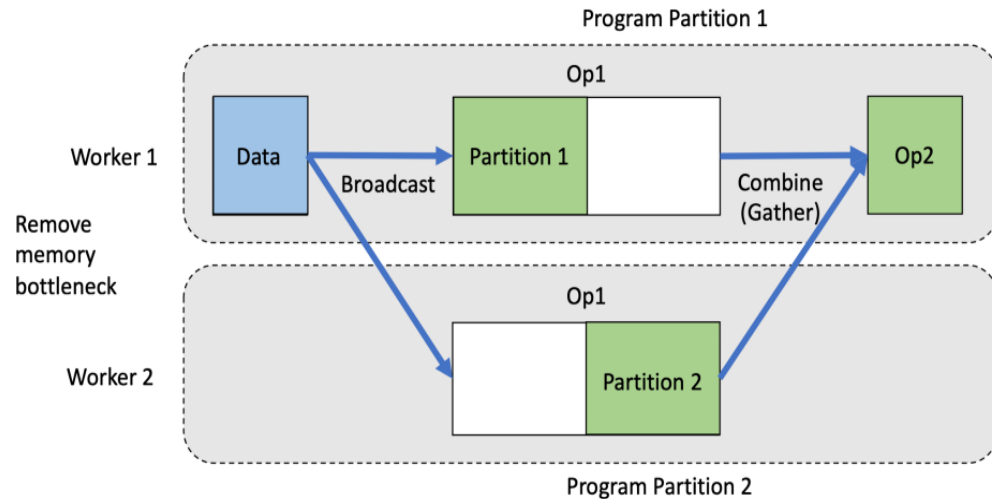


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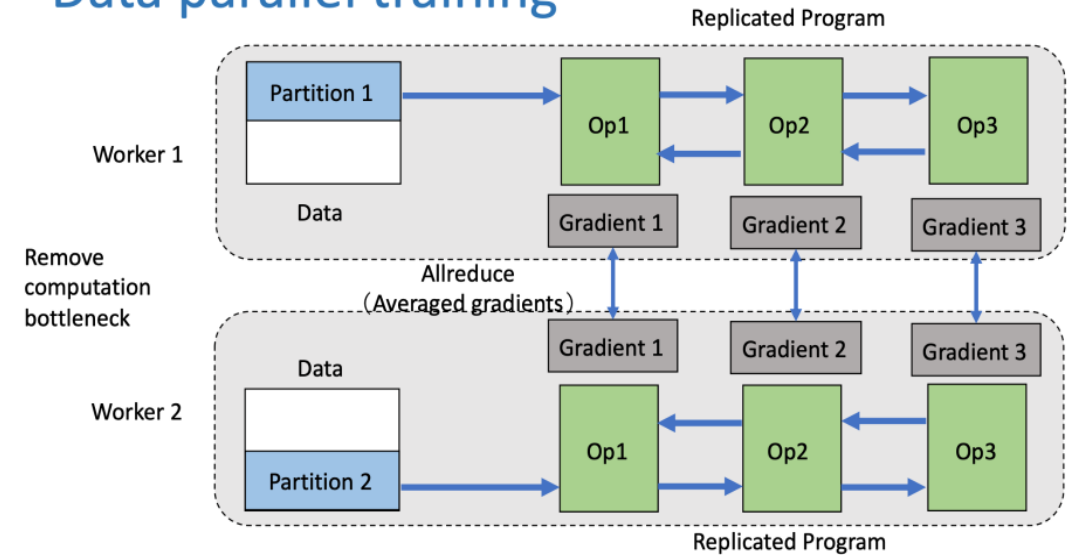
friendof(pedro, tom).
likes(X,Y) :- friendof(X, Y).
  
```

# Preliminaries II (analysis)

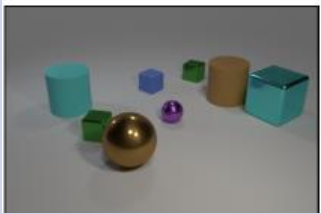

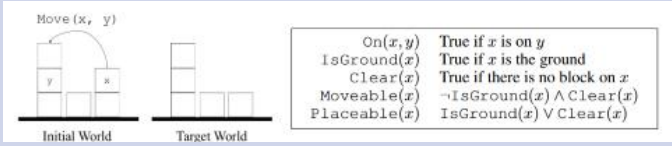
## Model parallel training: Intra-operator



## Data parallel training



# Introduction

Model	Submodules	Task	Dataset
NSCL by IBM/MIT	<ul style="list-style-type: none"> <li>Image Parser (Mask R-CNN)</li> <li>Question Parser (Open NMT)</li> <li>Symbolic Executor</li> </ul>	Query-driven Relational reasoning over images	CLEVR 
NS-DR by IBM/MIT	<ul style="list-style-type: none"> <li>Video Frame Parser (Mask R-CNN)</li> <li>Question Parser (Open NMT)</li> <li>Dynamics Predictor (Learned physics by PropNet)</li> <li>Symbolic Executor</li> </ul>	Query-driven relational reasoning over video	CLEVRER 
NLM by Google	<ul style="list-style-type: none"> <li>No Submodels</li> </ul>	Program-driven reasoning	Sort, Family tree, and Block's world 

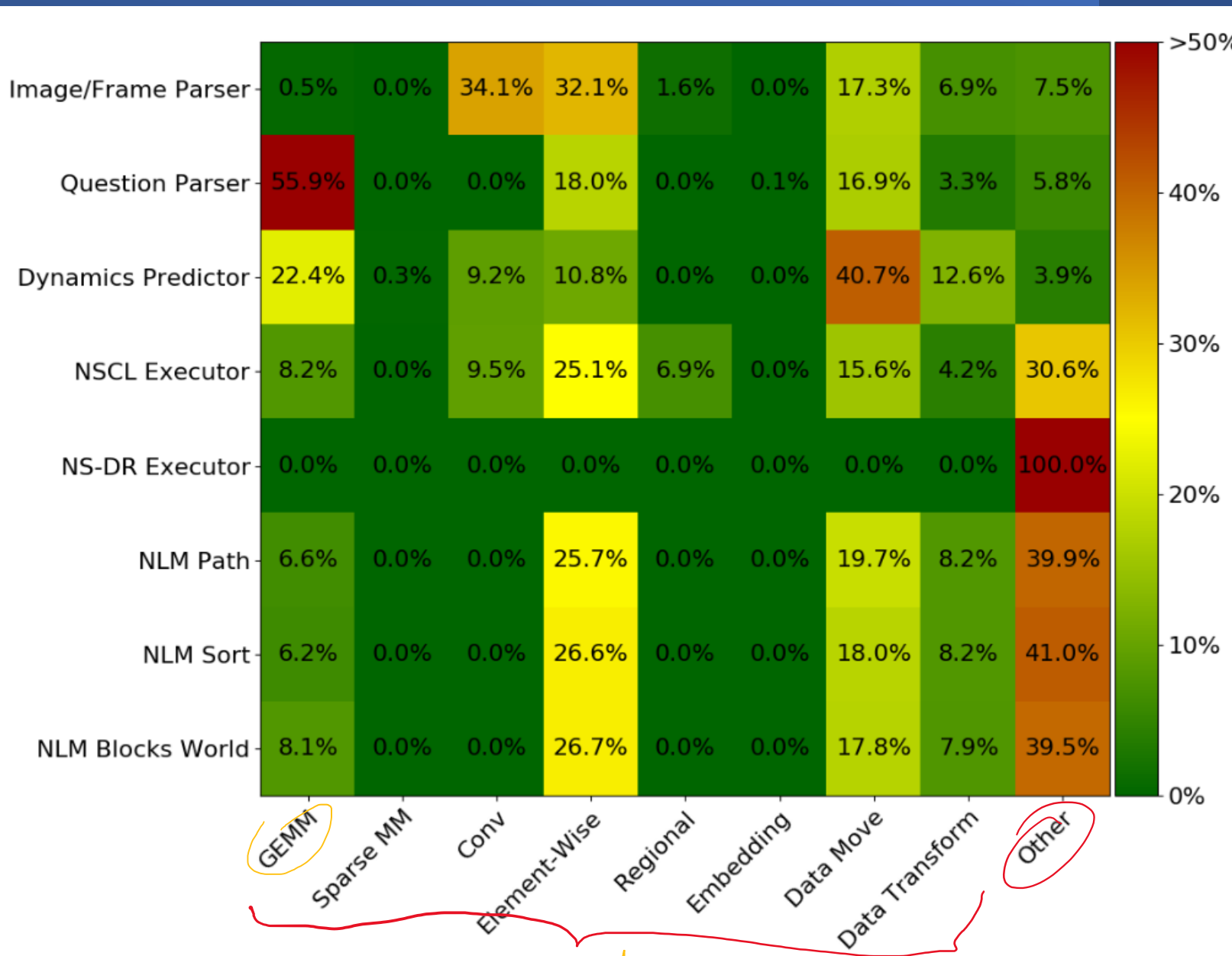
Motivation of  
function  
profiling

Identify potential  
parallelism

Identify bottlenecks  
to optimize

# Function profiling based on runtime

Workload	Examples	Comments
Dense matrix multiplication		Highly parallelizable unless one matrix's dimension is small.
Sparse matrix multiplication		Look-up for non-zero values
Convolution		Theoretically parallelizable, but practically challenging. Use im2col algorithm to convert convolution into a GeMM, but need a lot of data movement
Element wise tensor	Activation function, normalization	
Regional operations	Pooling	
Embedding lookup	One-hot to embedding	Parallelization is challenging: training != testing (look-up table)
Data movement	Tensor duplication, host-device transfer or tensor assignment	
Data transformation	Transpose, tensor reordering, coalescing	



Note:  
 → inference  
 ↳ single input

Operations



TABLE III  
 RUNTIMES AND RUNTIME BREAKDOWNS FOR SINGLE INPUTS TO THE MODELS DISCUSSED IN THIS PAPER.

Model	GEMM	Sparse MM	Conv	Element-Wise	Regional	Embedding	Data Move	Data Transform	Other	Total
Image/Frame Parser	0.19ms	0ms	11.8ms	11.1ms	0.54ms	0ms	6.0ms	2.4ms	2.6ms	34.6ms
Question Parser	166ms	0ms	0ms	53.5ms	0ms	0.27ms	50.1ms	9.9ms	17.3ms	297ms
Dynamics Predictor	715ms	9.9ms	294ms	345ms	0ms	0ms	1300ms	403ms	125ms	3200ms
NSCL Executor	39.9us	0us	46.4us	122.4us	33.5us	0.0us	76.0us	20.5us	149.5us	488.3us
NS-DR Executor	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	12.9ms*	12.9ms
NLM Path	1.2s	0s	0s	4.7s	0s	0s	3.6s	1.5s	7.3s	18.3s
NLM Sort	2.6s	0s	0s	11.1s	0s	0s	7.5s	3.4s	17.1s	41.7s
NLM Blocks World	635ms	0ms	0ms	2100ms	0ms	0ms	1400ms	618ms	3100ms	7850ms

↓  
 garbage  
 collection

## Results and Conclusion

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Question parser's computational time depends on input sequence's length *≈ 22 words*

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Dynamics predictor could be faster by optimizing coalescing.

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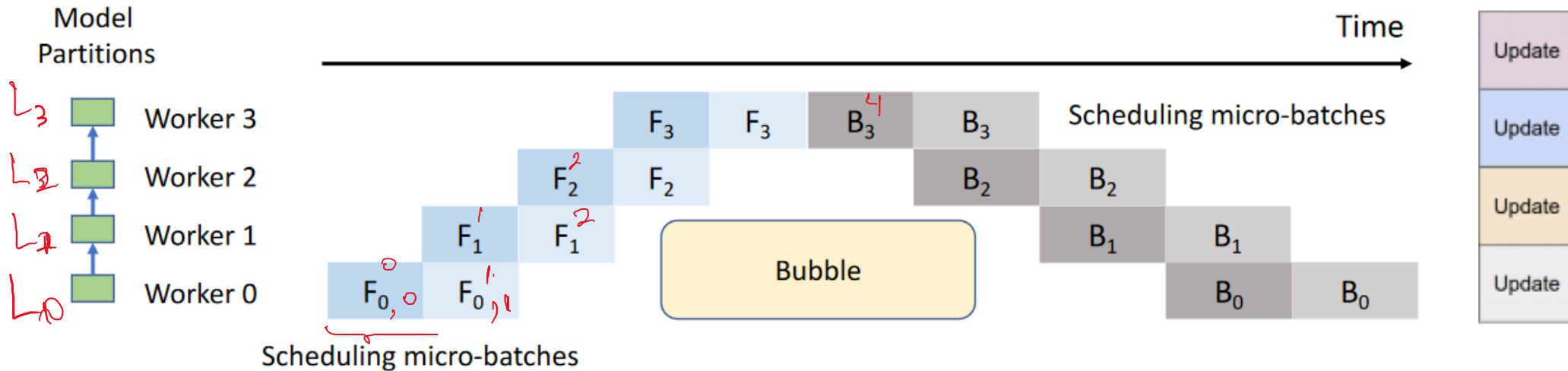
Symbolic program executors have small parallelization opportunities

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NLM also pose challenges for parallelization due to low operational intensity

# Pipeline parallelism 1.01

## Optimising micro-batch size



- **Small micro-batch** reduces bubble size; but incur large micro-batch scheduling overheads
- **Large micro-batch** incurs large bubble; but come with small micro-batch scheduling overheads
- Optimal micro-batch size must **balance bubble size and scheduling overheads**